

PARTITIONS OF UNITY IN $SL(2, \mathbb{Z})$, NEGATIVE CONTINUED FRACTIONS, AND DISSECTIONS OF POLYGONS

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ABSTRACT. We characterize sequences of positive integers (a_1, a_2, \dots, a_n) for which the 2×2 matrix $\begin{pmatrix} a_n & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_{n-1} & -1 \\ 1 & 0 \end{pmatrix} \cdots \begin{pmatrix} a_1 & -1 \\ 1 & 0 \end{pmatrix}$ is either the identity matrix Id , its negative $-\text{Id}$, or square root of $-\text{Id}$. This extends a theorem of Conway and Coxeter that classifies such solutions subject to a total positivity restriction.

1. INTRODUCTION AND MAIN RESULTS

Let $M_n(a_1, \dots, a_n) \in SL(2, \mathbb{Z})$ be the matrix defined by the product

$$(1.1) \quad M_n(a_1, \dots, a_n) := \begin{pmatrix} a_n & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_{n-1} & -1 \\ 1 & 0 \end{pmatrix} \cdots \begin{pmatrix} a_1 & -1 \\ 1 & 0 \end{pmatrix},$$

where (a_1, a_2, \dots, a_n) are positive integers. The goal of this paper is to describe all solutions of the following three equations

$$\begin{aligned} M_n(a_1, \dots, a_n) &= \text{Id}, && \text{(Problem I)} \\ M_n(a_1, \dots, a_n) &= -\text{Id}, && \text{(Problem II)} \\ M_n(a_1, \dots, a_n)^2 &= -\text{Id}. && \text{(Problem III)} \end{aligned}$$

Problem II, with a certain total positivity restriction, was studied in [7, 6] under the name of “frieze patterns”. The theorem of Conway and Coxeter [6] establishes a one-to-one correspondence between totally positive solutions of Problem II and triangulations of n -gons. Note also that Coxeter implicitly formulated Problem II in full generality, when he considered frieze patterns with zero and negative entries; see [8].

The following observations are obvious.

(a) Cyclic invariance: if (a_1, a_2, \dots, a_n) is a solution of one of the above problems, then (a_2, \dots, a_n, a_1) is also a solution of the same problem. It is thus often convenient to consider n -periodic infinite sequences $(a_i)_{i \in \mathbb{Z}}$ with the cyclic order convention $a_{i+n} = a_i$. Note however, that although the property of being a solution of Problem III is cyclically invariant, in this case the matrix $M_n(a_1, \dots, a_n)$ changes under cyclic permutation of (a_1, \dots, a_n) .

(b) The “doubling” $(a_1, \dots, a_n, a_1, \dots, a_n)$ of a solution of Problem II is a solution of Problem I, and the “doubling” of a solution of Problem III is a solution of Problem II.

A particular feature of Problem III (distinguishing it from Problems I and II) is that it is equivalent to a single Diophantine equation

$$\text{tr } M_n(a_1, \dots, a_n) = 0.$$

This equation was considered in [5], where the totally positive solutions were classified. It turns out that, every zero-trace element of $SL(2, \mathbb{Z})$ can be written in the form (1.1) for some positive integers (a_1, \dots, a_n) . For more details, see Section 4.

1.1. **The main result.** The following notion is our main combinatorial tool.

Definition 1.1. (a) We call a $3d$ -dissection a partition of a convex n -gon into sub-polygons by means of pairwise non-crossing diagonals, such that the number of vertices of every sub-polygon is a multiple of 3.

(b) The quiddity of a $3d$ -dissection of an n -gon is the (cyclically ordered) n -tuple of numbers (a_1, \dots, a_n) such that a_i is the number of sub-polygons adjacent to i th vertex of the n -gon.

In other words, a $3d$ -dissection splits an n -gon into triangles, hexagons, nonagons, dodecagons, etc. Classical triangulations are a very particular case of a $3d$ -dissection. The notion of quiddity is similar to that of Conway and Coxeter [6].

We will also consider *centrally symmetric* $3d$ -dissection of $2n$ -gons. Quiddities of such dissections are n -periodic, i.e., are doubled n -tuples of positive integers: $(a_1, \dots, a_n, a_1, \dots, a_n)$. We call a *half-quiddity* any n -tuple of consecutive numbers $(a_i, a_{i+1}, \dots, a_{i+n-1})$.

The following statement, proved in Section 3, is our main result.

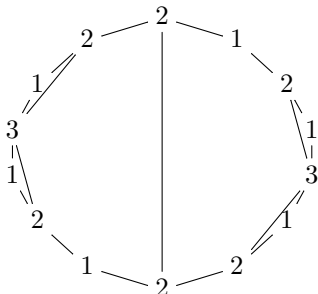
Theorem 1. (i) Every quiddity of a $3d$ -dissection of an n -gon is a solution of Problem I or Problem II. Conversely, every solution of Problem I or II is a quiddity of a $3d$ -dissection of an n -gon.

(i) A half-quiddity of a centrally symmetric solution of Problem II is a solution of Problem III, and every solution of Problem III is a half-quiddity of a centrally symmetric $3d$ -dissection of a $2n$ -gon.

To distinguish between the solutions of Problems I and II in Part (i) of the theorem, one needs to count the total number of sub-polygons with even number of vertices (6-gons, 12-gons,...) in the chosen $3d$ -dissection. If this number is *odd*, then the corresponding quiddity a solutions of Problem I, otherwise, it is a solutions of Problem II.

In order to explain how to construct a solution of Problems I-III starting from $3d$ -dissections we give here a simple example.

Example 1.2. Consider the following dissection of a tetradecagon ($n = 14$) into 4 triangles and 2 hexagons.



Label its vertices by the number of adjacent sub-polygons. Reading these numbers anti-clockwise along the border of the tetradecagon, one obtains a solution of Problem II

$$(a_1, \dots, a_{14}) = (2, 2, 1, 3, 1, 2, 1, 2, 2, 1, 3, 1, 2, 1).$$

Furthermore, the half-sequence $(a_1, \dots, a_7) = (2, 2, 1, 3, 1, 2, 1)$ is a solution of Problem III, since the $3d$ -dissection is centrally symmetric.

We formulate the problem of enumeration of solutions of Problems I-III. Counting the number of $3d$ -dissections of an n -gon can give the upper bound. We refer to [12] for a general theorem on enumeration of polygon dissections. Note that the Conway and Coxeter theorem implies that the totally positive solutions of Problem II are enumerated by triangulations of n -gons, so that the total number of solutions is given by the Catalan numbers.

To the best of our knowledge, $3d$ -dissections have not been considered in the literature. Let us mention that, since the work of Conway and Coxeter, triangulations of various geometric objects play important role in the subject; see, e.g., [1, 2]. Higher angulations of n -gons have also been considered; see [4, 16].

1.2. The surgery operations. We will give an inductive procedure of construction of all the solutions of Problems I-III. Consider the following two families of “local surgery” operations on solutions of Problems I-III.

- (a) The operations of the first type insert 1 into the sequence (a_1, a_2, \dots, a_n) , increasing the two neighboring entries by 1:

$$(1.2) \quad (a_1, \dots, a_i, a_{i+1}, \dots, a_n) \mapsto (a_1, \dots, a_i + 1, 1, a_{i+1} + 1, \dots, a_n).$$

Within the cyclic ordering of a_i , the operation is defined for all $1 \leq i \leq n$. The operations (1.2) preserve the set of solutions of each of the above problems.

- (b) The operations of the second type break one entry, a_i , replacing it by $a'_i, a''_i \in \mathbb{Z}_{>0}$ such that

$$a'_i + a''_i = a_i + 1,$$

and insert two consecutive 1's between them:

$$(1.3) \quad (a_1, \dots, a_i, \dots, a_n) \mapsto (a_1, \dots, a'_i, 1, 1, a''_i, \dots, a_n).$$

The operations (1.3) exchange the sets of solutions of Problems I and II, and preserve the set of solutions of Problem III.

The crucial difference between these two classes of operations is that every operation (1.2) increases the number of sub-polygons of a $3d$ -dissection by 1, while an operation (1.3) keeps this number unchanged. Indeed, an operation (1.2) consists in a gluing an extra “exterior” triangle, while an operation (1.3) selects one sub-polygon and increases the number of its vertices by 3. For more details, see Section 3. Note also that for a given n , there are exactly n different operations of type (1.2), while the total number of different operations of type (1.3) is equal to $a_1 + \dots + a_n$. Every operation (1.2) transforms n into $n + 1$, while every operation (1.3) transforms n into $n + 3$.

The following statement, proved in Section 2, is an “algorithmic version” of Theorem 1.

Theorem 2. (i) *If $n = 2$, then Problem III has exactly two solutions:*

$$(1.4) \quad (a_1, a_2) = (1, 2), \text{ or } (2, 1),$$

and every solution of Problem III can be obtained from (1.4) by a sequence of operations (1.2) and (1.3).

(ii) *If $n = 3$, then Problem II has a unique solution:*

$$(1.5) \quad (a_1, a_2, a_3) = (1, 1, 1),$$

and every solution of Problem I (resp. II) can be obtained from (1.5) by a sequence of operations (1.2) and (1.3), such that the total number of operations (1.3) is odd (resp. even).

Note that the operations (1.2) are very well known. They were used by Conway and Coxeter [6]; see also [10, 3] and many other sources. In particular, the totally positive solutions of Problem II are precisely the solutions obtained by a sequence of operations (1.2); see Appendix. The operations (1.3) seem to be new. They change the combinatorial nature of solutions (from triangulations to $3d$ -dissections), they also have a geometric meaning in terms of the homotopy class of a curve on the projective line; see Section 5.

1.3. **Motivation.** The following topics are related to Problems I-III, and motivated our study.

- a) The theory of negative continued fractions

$$[a_1, a_2, \dots, a_n] = a_1 - \frac{1}{a_2 - \frac{1}{\ddots - \frac{1}{a_n}}}$$

is relevant for the subject of this paper, although in this theory one usually considers $a_i \geq 2$ and the matrix $M_n(a_1, \dots, a_n)$ is hyperbolic. Some ideas of the theory have found application to Farey sequences; see [22, 13, 20, 16].

- b) The matrix $M_n(a_1, \dots, a_n)$ is the monodromy matrix of the discrete Sturm-Liouville equation

$$(1.6) \quad V_{i-1} - a_i V_i + V_{i+1} = 0.$$

Solutions of Problem I (resp. II) are in *one-to-one correspondence* with equations (1.6) with positive integer n -periodic coefficients a_i , such that every solution $(V_i)_{i \in \mathbb{Z}}$ of the equation is periodic (resp. antiperiodic):

$$V_{i+n} = V_i \quad (\text{resp. } V_{i+n} = -V_i),$$

for all i . Sturm oscillation theory (see, e.g., [21]), and in particular the notion of rotation number [11], can then be applied to give a geometric invariant separating the classes of solutions of Problems I-III, counting the number of operations (1.3); see Section 5.

- c) The classical moduli space $\mathcal{M}_{0,n}$ of configurations of n points in \mathbb{CP}^1 has a structure of algebraic variety that can be defined as follows:

$$\mathcal{M}_{0,n} = \{(a_1, \dots, a_n) \in \mathbb{C}^n \mid M_n(a_1, \dots, a_n) = -\text{Id}\},$$

see [19]. Theorem 1 describes a set of rational points of this variety.

- d) Combinatorics of Coxeter's frieze patterns [7, 6]. Coxeter's friezes became an active area of research; see [18] and references therein. Although this is not the main subject of the paper, we outline in Section 6 the class of Coxeter's friezes corresponding to arbitrary solutions of Problems II and III. Note also that classical Farey sequences can be understood as very particular cases of Coxeter friezes; see [7] (and also [20]). In particular, the index of a Farey sequence defined in [13], is a totally positive solution of Problem II.

2. PROOF OF THEOREM 2

In this section we prove Theorem 2 and give some of its simplest corollaries.

2.1. **Induction basis.** Let us first consider the simplest cases.

- a) If $n = 2$, then the matrix $M_2(a_1, a_2)$ is as follows:

$$\begin{pmatrix} a_2 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_1 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} a_1 a_2 - 1 & -a_2 \\ a_1 & -1 \end{pmatrix},$$

with $a_1, a_2 > 0$. Since this matrix cannot be $\pm \text{Id}$, Problems I and II have no solutions.

Consider Problem III. The condition $M_2(a_1, a_2)^2 = -\text{Id}$ implies that the trace of this matrix vanishes, so that the coefficients a_1, a_2 must satisfy the equation $a_1 a_2 = 2$. The only positive integers satisfying this equation are $(a_1, a_2) = (2, 1)$ and $(1, 2)$.

b) Consider the case $n = 3$ and assume that the sequence (a_1, a_2, a_3) contains two consecutive 1's. Set $(a_1, a_2, a_3) = (a, 1, 1)$. The matrix $M_3(a_1, a_2, a_3)$ is then given by

$$\begin{pmatrix} a & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 1-a \\ 0 & -1 \end{pmatrix}.$$

Hence Problem II has one solution $(1, 1, 1)$, corresponding to $a = 1$, while Problems I and III have no solutions.

2.2. Surgery operations on matrices. Let us analyze how the operations (1.2) and (1.3) act on the matrix (1.1). This is just an elementary computation.

An operation (1.2) replaces the product of two elementary matrices

$$\begin{pmatrix} a_{i+1} & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_i & -1 \\ 1 & 0 \end{pmatrix}$$

in the expression for $M_n(a_1, \dots, a_n)$ by

$$(2.1) \quad \begin{pmatrix} a_{i+1} + 1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_i + 1 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} a_i a_{i+1} - 1 & -a_i \\ a_{i+1} & -1 \end{pmatrix} \\ = \begin{pmatrix} a_{i+1} & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_i & -1 \\ 1 & 0 \end{pmatrix}.$$

Therefore, an operation (1.2) does not change the matrix:

$$M_{n+1}(a_1, \dots, a_i + 1, 1, a_{i+1} + 1, \dots, a_n) = M_n(a_1, \dots, a_n).$$

It follows that the operations (1.2) preserve the sets of solutions of Problems I-III.

Consider now an operation (1.3). Since

$$(2.2) \quad \begin{pmatrix} a_i'' & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_i' & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 - a_i' - a_i'' & 1 \\ -1 & 0 \end{pmatrix} = - \begin{pmatrix} a_i & -1 \\ 1 & 0 \end{pmatrix},$$

the matrix $M_n(a_1, \dots, a_n)$ changes its sign. Hence the operations (1.3) preserve the set of solutions of Problem III. Furthermore, if the number of the operations (1.3) is even, then the sequence of operations also preserves the set of solutions of Problems I and II.

2.3. Induction step. We need the following lemma, which was essentially proved in [6] for Problem II.

Lemma 2.1. *Given a solution (a_1, \dots, a_n) of Problem I, II, or III, there exists at least one value of $1 \leq i \leq n$, such that $a_i = 1$.*

Proof. Assume that $a_i \geq 2$ for all i , and consider the solution $(V_i)_{i \in \mathbb{Z}}$ of the equation (1.6) with initial conditions $(V_0, V_1) = (0, 1)$. Since $V_{i+1} = a_i V_i - V_{i-1}$, we see by induction that $V_{i+1} > V_i$ for all i . Therefore, the solution $(V_i)_{i \in \mathbb{Z}}$ grows and cannot be periodic.

The matrix $M_n(a_1, \dots, a_n)$ is the monodromy matrix of (1.6). More precisely, let $(V_i)_{i \in \mathbb{Z}}$ be a solution of the equation (1.6). Then for the vector $(V_{i+1}, V_i)^t$, we have

$$\begin{bmatrix} V_{i+1} \\ V_i \end{bmatrix} = \begin{pmatrix} a_i & -1 \\ 1 & 0 \end{pmatrix} \begin{bmatrix} V_i \\ V_{i-1} \end{bmatrix}, \quad \dots, \quad \begin{bmatrix} V_{i+n} \\ V_{i+n-1} \end{bmatrix} = M_n(a_i, \dots, a_{i+n}) \begin{bmatrix} V_i \\ V_{i-1} \end{bmatrix}.$$

Suppose first that $M_n(a_1, \dots, a_n) = \text{Id}$. Then every solution of (1.6) must be periodic, which is a contradiction.

If now $M_n(a_1, \dots, a_n) = -\text{Id}$ or $M_n(a_1, \dots, a_n)^2 = -\text{Id}$, then we can use the doubling argument to conclude that every solution of (1.6) must be $2n$ -periodic or $4n$ -periodic, respectively. \square

We are ready to prove that every solution of Problems I-III can be obtained from the elementary solutions (1.5) and (1.4) by a sequence of the operations (1.2) and (1.3).

Given a solution (a_1, \dots, a_n) , by Lemma 2.1 there exists at least one coefficient a_i which is equal to 1. There are then two possibilities:

- (a) both $a_{i-1}, a_{i+1} \geq 2$;
- (b) there are two consecutive 1's, say $a_i = a_{i+1} = 1$, i.e., the chosen solution has the following "fragment": $(\dots, a_{i-1}, 1, 1, a_{i+2}, \dots)$.

In the case (a), consider the $(n-1)$ -tuple

$$(a_1, \dots, a_{i-2}, a_{i-1} - 1, a_{i+1} - 1, a_{i+2}, \dots, a_n).$$

Clearly, the solution (a_1, \dots, a_n) can be obtained from this $(n-1)$ -tuple by an operation (1.2). Equation (2.1) implies that the matrix $M_{n-1}(a_1, \dots, a_{i-2}, a_{i-1} - 1, a_{i+1} - 1, a_{i+2}, \dots, a_n)$ remains equal to $M_n(a_1, \dots, a_n)$.

In the case (b), take the $(n-3)$ -tuple

$$(a_1, \dots, a_{i-2}, a_{i-1} + a_{i+2} - 1, a_{i+3}, \dots, a_n).$$

The solution (a_1, \dots, a_n) is then a result of the operation (1.3) applied to the coefficient $a_{i-1} + a_{i+2} - 1$. Equation (2.2) implies that $M_{n-3}(a_1, \dots, a_{i-2}, a_{i-1} + a_{i+2} - 1, a_{i+3}, \dots, a_n) = M_n(a_1, \dots, a_n)$.

The above inverse operations (1.2) and (1.3) can always be applied, unless $n = 2$, or unless $n = 3$ and there are at least two consecutive 1's.

Theorem 2 is proved. \square

2.4. Simple corollaries. An immediate consequence of Theorem 2 is the following upper bound for the coefficients.

Corollary 2.2. *If (a_1, a_2, \dots, a_n) is a solution of one of Problems I, II, or III, then*

- (i) $a_i \leq n - 5$ (Problem I);
- (ii) $a_i \leq n - 2$ (Problem II);
- (iii) $a_i \leq n$ (Problem III).

Proof. The operations (1.3) cannot increase the values of the coefficients a_i , while the operations (1.2) simultaneously increase n and two coefficients by 1. \square

The next corollary gives expressions for the total sum of the coefficients.

Corollary 2.3. *(i) If (a_1, a_2, \dots, a_n) is a solution of one of Problems I or II obtained from the initial solution $(a_1, a_2, a_3) = (1, 1, 1)$ by applying a sequence of S operations (1.2) and R operations (1.3), then*

$$(2.3) \quad \begin{aligned} a_1 + a_2 + \dots + a_n &= 3S + 3R + 3 \\ &= 3n - 6R - 6. \end{aligned}$$

(ii) If (a_1, a_2, \dots, a_n) is a solution of Problem III obtained from one of the initial solutions $(a_1, a_2) = (2, 1)$ or $(1, 2)$ by applying a sequence of S operations (1.2) and R operations (1.3), then

$$(2.4) \quad \begin{aligned} a_1 + a_2 + \dots + a_n &= 3S + 3R + 3 \\ &= 3n - 6R - 3. \end{aligned}$$

Proof. Both the operations (1.3) and (1.2) add 3 to the total sum of the coefficients. Furthermore, the operations (1.2) (resp. (1.3)) increase n by 1 (resp. by 3). \square

Note that the numbers S and R depend only on the solution (a_1, a_2, \dots, a_n) (and independent of the choice of the sequence of operations producing the solution). The simplest case $R = 0$ is considered in Appendix.

2.5. Solutions of Problem I for small n . Let us give several examples constructed using the inductive procedure provided by Theorem 2. We start with the list of solutions of Problem I for $n \leq 8$.

- (a) Part (i) of Corollary 2.2 implies that Problem I has no solutions for $n \leq 5$.
- (b) For $n = 6$, Problem I has the unique solution

$$(a_1, a_2, a_3, a_4, a_5, a_6) = (1, 1, 1, 1, 1, 1)$$

obtained from (1.5) by one operation (1.3).

- (c) For $n = 7$, one has 7 different solutions:

$$(2.5) \quad (a_1, a_2, a_3, a_4, a_5, a_6, a_7) = (2, 1, 2, 1, 1, 1, 1)$$

and its cyclic permutations.

- (d) For $n = 8$, one has 34 different solutions, namely

$$(2.6) \quad (a_1, \dots, a_8) = (3, 1, 1, 1, 1, 2, 2, 1), \quad (3, 1, 2, 1, 1, 1, 2, 1), \quad (2, 2, 1, 2, 1, 1, 2, 1), \quad (2, 1, 2, 1, 2, 1, 2, 1),$$

and their reflections and cyclic permutations.

2.6. Solutions of Problem II for small n . Below is the list of solutions of Problem II for $n \leq 10$.

- (a) For $n \leq 8$ all solutions of Problem II are given by Conway-Coxeter's solutions, and correspond to triangulations of n -gons; see Appendix. The number of solutions for a given n is thus equal to the Catalan number C_{n-2} , where $C_n = \frac{1}{n+1} \binom{2n}{n}$.
- (b) For $n = 9$, in addition to 429 Conway-Coxeter solutions, there is exactly one extra solution:

$$(2.7) \quad (a_1, \dots, a_9) = (1, 1, 1, 1, 1, 1, 1, 1, 1).$$

- (c) For $n = 10$, in addition to 1430 Conway-Coxeter solutions, there are 15 solutions:

$$(2.8) \quad (a_1, \dots, a_{10}) = (2, 1, 1, 1, 1, 2, 1, 1, 1, 1), \quad (2, 1, 2, 1, 1, 1, 1, 1, 1, 1),$$

and their cyclic permutations.

- In Section 3.3 we will give the dissections of n -gons corresponding to the above examples.

3. THE COMBINATORIAL MODEL: $3d$ -DISSECTIONS

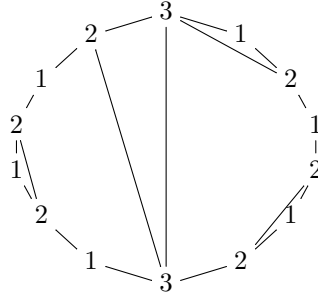
In this section we prove Theorem 1 deducing it from Theorem 2. Using the combinatorics of $3d$ -dissections, we then obtain the formulas for the numbers of surgery operations for a given solution of Problems I or II. Finally, we revisit the examples from Sections 2.5 and 2.6 and give their combinatorial realizations.

3.1. Proof of Theorem 1. Part (i). Consider a solution (a_1, \dots, a_n) of Problem I or II. We want to prove that there exists a $3d$ -dissection of an n -gon such that its quiddity is precisely the chosen solution.

We proceed by induction on n . By Theorem 2, the chosen solution can be obtained from the initial solution (1.5) by a series of operations (1.2) and (1.3). Consider the solution (of length $n - 1$ or $n - 3$) obtained by the same sequence but without the last operation. By induction assumption, this solution corresponds to some $3d$ -dissection, say D , (of an $(n - 1)$ -gon or an $(n - 3)$ -gon). There are then two possibilities.

- (a) If the last operation in the series is that of type (1.2), then the solution corresponds to the angulation D with extra exterior triangle glued to the edge $(i, i + 1)$.

the following $3d$ -dissection of the tetradecagon (“Klimenko’s dissection”)



is not centrally symmetric, but the corresponding quiddity is 7-periodic and provides seven different solutions of Problem III.

3.2. Counting the surgery operations. Consider a solution of Problem I or II corresponding to some $3d$ -dissection. Denote by N_d is the number of $3d$ -gons in the $3d$ -dissection.

Proposition 3.2. *Given a solution of Problem I or II constructed from (1.5) by a sequence of S operations (1.2) and R operations (1.3),*

(i) *The number S counts the total number of sub-polygons except for the initial one:*

$$(3.1) \quad S = \sum_{d \leq \lfloor \frac{n}{3} \rfloor} N_d - 1.$$

(ii) *The number of operations of the second type is the weighted sum*

$$(3.2) \quad R = \sum_{d \leq \lfloor \frac{n}{3} \rfloor} (d - 1) N_d.$$

In other words, to calculate R , one ignores the triangles, counts hexagons, counts nonagons 2 times, dodecagons 3 times, etc.

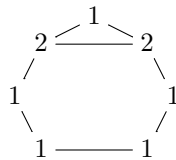
Proof. An operation (1.2) consists in a gluing a triangle. It increases the total number of sub-polygons by 1. This implies (3.1).

We have proved (see the proof of Theorem 1) that an operation (1.3) does not change the total number of sub-polygons of a $3d$ -dissection, but adds 3 new vertices to one of the existing sub-polygons. Hence (3.2). \square

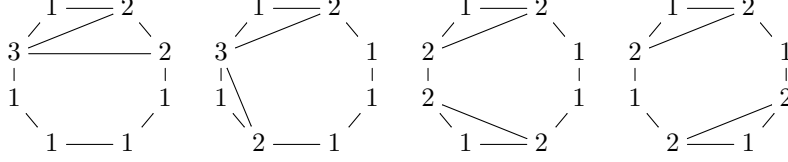
3.3. Examples. Let us give combinatorial entities of the examples from Section 2.

(a) Consider again the solutions of Problem I for small n ; see Section 2.5. For $n = 6$ the unique solution $(a_1, \dots, a_6) = (1, \dots, 1)$ is given by the hexagon without interior diagonals.

For $n = 7$ the unique modulo cyclic permutations solution (2.5) corresponds to a triangle glued to an hexagon



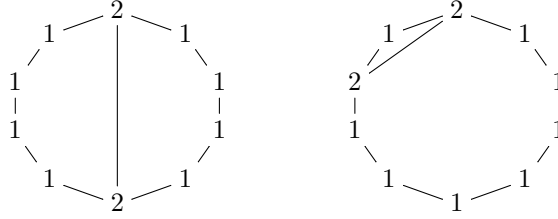
For $n = 8$ the solutions of Problem I correspond to dissections of the octagon into hexagon and two triangles. There are exactly 4 such dissections (modulo reflections and rotations):



in full accordance with (2.6).

(b) Consider now the solutions of Problem II discussed in Section 2.6. For $n = 9$ the solution (2.7) obviously corresponds to the nonagon with no dissection. For $n = 10$ there are two possibilities: two glued hexagons and a triangle glued to a nonagon

(3.3)



This corresponds (modulo cyclic permutations) to the solutions (2.8). The first of the above dissections, i.e., the “hexagonal” one, is quite remarkable and will play an important role in the next section.

4. PROBLEM III AND ZERO-TRACE MATRICES

An elementary observation shows that Problem III is equivalent to a single Diophantine equation, namely $\text{tr } M_n(a_1, \dots, a_n) = 0$. We show that $3d$ -dissections allow one to construct all integer zero-trace unimodular matrices.

4.1. The “Rotundus” polynomial. The trace of the matrix (1.1) is a beautiful cyclically invariant polynomial in a_1, \dots, a_n , that we denote by $R_n(a_1, \dots, a_n)$. The first examples are:

$$\begin{aligned} R_1(a) &= a, \\ R_2(a_1, a_2) &= a_1 a_2 - 2, \\ R_3(a_1, a_2, a_3) &= a_1 a_2 a_3 - a_1 - a_2 - a_3, \\ R_4(a_1, a_2, a_3, a_4) &= a_1 a_2 a_3 a_4 - a_1 a_2 - a_2 a_3 - a_3 a_4 - a_1 a_4 + 2, \\ R_5(a_1, a_2, a_3, a_4, a_5) &= a_1 a_2 a_3 a_4 a_5 \\ &\quad - a_1 a_2 a_3 - a_2 a_3 a_4 - a_3 a_4 a_5 - a_1 a_4 a_5 - a_1 a_2 a_5 \\ &\quad + a_1 + a_2 + a_3 + a_4 + a_5. \end{aligned}$$

The polynomial $R_n(a_1, \dots, a_n)$ was called the “Rotundus” in [5], where it is proved that $R_n(a_1, \dots, a_n)$ can also be calculated as the Pfaffian of a certain skew-symmetric matrix. Note that $R_n(a_1, \dots, a_n)$ is the polynomial part of the rational function

$$a_1 a_2 \cdots a_n \left(1 - \frac{1}{a_1 a_2}\right) \left(1 - \frac{1}{a_2 a_3}\right) \cdots \left(1 - \frac{1}{a_n a_1}\right).$$

4.2. The “Rotundus equation”. An n -tuple of positive integers (a_1, \dots, a_n) is a solution of Problem III if and only if $\text{tr } M_n(a_1, \dots, a_n) = 0$. In other words, we have the following.

Proposition 4.1. *Every solution of Problem III is a solution of the equation*

$$(4.1) \quad R_n(a_1, \dots, a_n) = 0,$$

and vice-versa.

Proof. A trace zero element of $SL(2, \mathbb{Z})$ has eigenvalues i and $-i$. This is equivalent to the fact that it squares to $-\text{Id}$. \square

Remark 4.2. Note also that every solution of Problem I or II satisfies the equation $R_n(a_1, \dots, a_n) = 2$ or -2 , respectively. However, the converse is false: a solution of one of these equations is not necessarily a solution of Problem I or II. It is also easy to see that, unlike (4.1), the equation $R_n(a_1, \dots, a_n) = \pm 2$ has infinitely many positive integer solutions for sufficiently large n . For instance, one has $R_n(a, 1, 1) = -2$ for any a .

4.3. The list of solutions of Problem III for small n . Let us give a complete list of solutions of Problem III for $n \leq 6$.

(a) For $n = 2, 3$, and 4 , all the solutions are given by centrally symmetric triangulations of a quadrilateral (2), hexagon (6), and octagon (20), respectively.

(b) For $n = 5$, besides 70 solutions corresponding to centrally symmetric triangulations of the decagon (see Example 7.9 below), one obtains 5 additional solutions:

$$(a_1, a_2, a_3, a_4, a_5) = (2, 1, 1, 1, 1)$$

and its cyclic permutations. These 5 new solutions are obtained from (1.4) by applying one operation (1.3).

The corresponding centrally symmetric dissection of a decagon is the hexagonal dissection in (3.3).

(c) For $n = 6$, besides 252 solutions corresponding to centrally symmetric triangulations of the dodecagon, one gets 26 additional solutions:

$$(a_1, a_2, a_3, a_4, a_5, a_6) = (3, 1, 2, 1, 1, 1), \quad (2, 2, 1, 2, 1, 1), \quad (2, 1, 2, 1, 2, 1),$$

their cyclic permutations and reflections.

We mention that the sequence $2, 6, 20, 75, 278, \dots$ corresponding to the total number of solutions of Problem III is not in the OEIS.

4.4. Generating zero-trace matrices. We show that every zero-trace 2×2 unimodular matrix can be written in the form (1.1). This information is interesting since integer zero-trace matrices code integer binary quadratic forms. Indeed, the matrix $\begin{pmatrix} \alpha & -\beta \\ \gamma & -\alpha \end{pmatrix}$, is associated with the quadratic form $\beta x^2 + 2\alpha xy + \gamma y^2$, and this correspondence is $SL(2, \mathbb{Z})$ -invariant.

Theorem 3. *Every zero-trace element of $SL(2, \mathbb{Z})$ can be written in the form $M_n(a_1, \dots, a_n)$, for some n -tuple of positive integers (a_1, \dots, a_n) .*

Proof. First, we observe that

$$(4.2) \quad M_5(1, 1, 2, 1, 1) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

To obtain the transposed matrix, one takes $M_8(1, 1, 2, 1, 1, 1, 1, 1)$.

Besides the matrix (4.2), any other zero-trace matrix in $SL(2, \mathbb{Z})$ has all its entries non-zero. Consider a matrix $\begin{pmatrix} \alpha & -\beta \\ \gamma & -\alpha \end{pmatrix}$, where the integers $\alpha, \beta, \gamma > 0$ such that $\beta\gamma = \alpha^2 + 1$. Assuming that $\gamma > \alpha > \beta$ and

using the Euclidean algorithm, we find two decreasing sequences (α_i, β_i) starting with $(\alpha_1, \beta_1) = (\alpha, \beta)$ and ending with $(0, 1)$ such that every 2×2 minor of the following matrix

$$\begin{pmatrix} \alpha & -\beta & \beta_2 & -\beta_3 & \beta_4 & -\beta_5 & \cdots \\ \gamma & -\alpha & \alpha_2 & -\alpha_3 & \alpha_4 & -\alpha_5 & \cdots \end{pmatrix}$$

equals 1. Therefore, both sequences of positive integers (α_i, β_i) are solutions of the same linear equation $V_{i+1} = a_i V_i - V_{i-1}$, and one obtains

$$\begin{pmatrix} \alpha & -\beta \\ \gamma & -\alpha \end{pmatrix} = M_n(a_1, \dots, a_n).$$

Note that the fact that (α_i, β_i) are positive implies that the sequence (a_1, \dots, a_n) is a quiddity of a triangulation.

To obtain the “transposed” matrix $\begin{pmatrix} \alpha & -\gamma \\ \beta & -\alpha \end{pmatrix}$, again with $\alpha, \beta, \gamma > 0$, one reads the above solution in the opposite sense: (a_n, \dots, a_1) . To change the sign of the matrix and get $\begin{pmatrix} -\alpha & \beta \\ -\gamma & \alpha \end{pmatrix}$, one adds three consecutive 1’s and takes the $(n+3)$ -tuple $(a_1, \dots, a_n, 1, 1, 1)$. Finally, to obtain the matrix with the negative second row $\begin{pmatrix} \alpha & \beta \\ -\gamma & -\alpha \end{pmatrix}$, one considers the quiddities of the form $(1, 1, a_1, \dots, a_n, 1, 1)$.

We have proved that every zero-trace unimodular matrix is of the form $M_n(a_1, \dots, a_n)$ for some positive integers (a_n, \dots, a_1) . \square

Remark 4.3. It is interesting to mention that it is impossible to obtain the simplest zero-trace matrix (4.2) with Conway-Coxeter’s quiddities of triangulations. If (a_1, \dots, a_n) is a quiddity of a triangulation, then the matrix $M_n(a_1, \dots, a_n)$ is of the form $\begin{pmatrix} \alpha & -\beta \\ \gamma & -\alpha \end{pmatrix}$, where $\alpha, \beta, \gamma > 0$. The simplest zero-trace matrix that can be generated by triangulations is

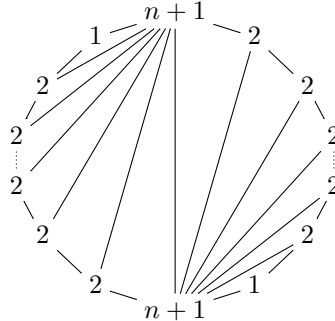
$$M_2(1, 2) = \begin{pmatrix} 1 & -1 \\ 2 & -1 \end{pmatrix},$$

corresponding to the quadrilateral. For more complicated triangulations the coefficients a, b, c of the matrix grow. The matrix (4.2) corresponds to the hexagonal dissection in (3.3).

Let us give more examples.

Example 4.4. (a) Choosing $(a_1, \dots, a_n) = (1, 2, \dots, 2, n+1)$, with 2 repeated $n-1$ times, one obtains the matrix $\begin{pmatrix} n & -1 \\ n^2+1 & -n \end{pmatrix}$. This is the quiddity of a centrally symmetric triangulation of a $2n$ -gon

with two “accumulating points”:



Replacing the exterior triangle with an hexagon, one obtains a $3d$ -dissection that generates the quiddity $(a_1, \dots, a_{n+3}) = (1, 1, 1, 1, 2, \dots, 2, n+1)$. This gives the same matrix with the opposite sign.

Remark 4.5. Every zero-trace matrix can be written in the form (1.1) in many different ways. In order to make this presentation canonical, it is convenient to introduce the notion of “reduced” n -tuple. This is an n -tuple that does not contain fragments $(a', 1, a'')$ and $(a', 1, 1, a'')$ with $a', a'' > 1$, and more than three consecutive 1’s in the ends. We do not dwell on this interesting problem here and hope to study it elsewhere.

5. THE ROTATION INDEX

In this section we apply the Sturm theory of linear difference equations to define a geometric invariant of solutions of Problem I, II, and III. It is given by the index of a star-shaped broken line in \mathbb{R}^2 , that can also be understood as the homotopy class of an n -gon in the projective line, or as the rotation number of the equation (1.6). The defined invariant is a *(half)integer*. We prove that the index actually counts the number of operations of the second type (1.3) needed for a solution to be obtained from the initial one.

5.1. Index of a star-shaped broken line. Recall the following geometric notions.

- a) The index of a smooth closed plane curve is the number of rotations of its tangent vector.
- b) A smooth oriented (parametrized) closed curve $\gamma(t)$ in \mathbb{R}^2 , where $t \in [0, 1]$ and $\gamma(t+1) = \gamma(t)$ is *star-shaped* if it does not contain the origin, and the tangent vector $\dot{\gamma}(t)$ is transversal to $\gamma(t)$, for all t .
- c) The index of a star-shaped curve can be calculated as the homotopy class of the projection of $\gamma(t)$ to \mathbb{RP}^1 in the tautological line bundle $\mathbb{R}^2 \setminus \{0\} \rightarrow \mathbb{RP}^1$, i.e., the rotation number around the origin.

Definitions a)–c) obviously extend to piecewise smooth curves, in particular to *broken lines*.

Example 5.1. The index of the following star-shaped broken lines:



is equal to 1 and 2, respectively.

Furthermore, if the curve is *antiperiodic*, that is if $\gamma(t+1) = -\gamma(t)$, the index is still well defined, but takes half-integer values.

Example 5.2. The index of the following star-shaped antiperiodic broken lines:



is equal to $\frac{1}{2}$ and $\frac{3}{2}$, respectively.

5.2. The broken line of a matrix $M_n(a_1, \dots, a_n)$. Given a solution (a_1, \dots, a_n) of Problem I, II, or III, let us construct a star-shaped broken line in \mathbb{R}^2 . Consider the corresponding discrete Sturm-Liouville equation

$$V_{i+1} = a_i V_i - V_{i-1},$$

where the set of coefficients a_i is understood as an infinite n -periodic sequence $(a_i)_{i \in \mathbb{Z}}$. Choose two linearly independent solutions, $V^{(1)} = (V_i^{(1)})_{i \in \mathbb{Z}}$ and $V^{(2)} = (V_i^{(2)})_{i \in \mathbb{Z}}$. One then has a sequence of points in \mathbb{R}^2 :

$$V_i = (V_i^{(1)}, V_i^{(2)}),$$

These points form a broken star-shaped line. Indeed, the determinant

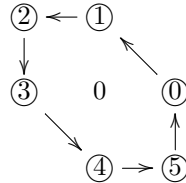
$$W(V^{(1)}, V^{(2)}) := \begin{vmatrix} V_{i+1}^{(1)} & V_i^{(1)} \\ V_{i+1}^{(2)} & V_i^{(2)} \end{vmatrix},$$

usually called the *Wronski determinant*, is constant, i.e., does not depend on i . Therefore, the sequence of points $(V_i)_{i \in \mathbb{Z}}$ in \mathbb{R}^2 always rotates around the origin in the same (positive or negative, depending on the choice of the two solutions) direction. Note that a different choice of the solutions $V^{(1)}$ and $V^{(2)}$ gives the same broken line, modulo a linear coordinate transformation in \mathbb{R}^2 .

If $M_n(a_1, \dots, a_n) = \text{Id}$ (resp. $-\text{Id}$), then the broken line thus constructed is periodic, i.e., $V_{i+n} = V_i$ (resp. anti-periodic, $V_{i+n} = -V_i$). We will be interested in the *index* of this broken line.

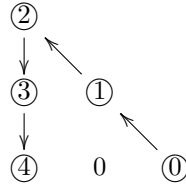
Remark 5.3. Note that the index of an antiperiodic star-shaped broken line is a well-defined half-integer. If $M_n(a_1, \dots, a_n)^2 = -\text{Id}$, then, using the doubling procedure, we can still define the index of the corresponding star-shaped broken line as a multiple of $\frac{1}{2}$.

Example 5.4. (a) Consider the sequence $(a_1, \dots, a_6) = (1, 1, 1, 1, 1, 1)$, which is the solution of Problem I obtained from $(1, 1, 1)$ by applying one operation (1.3). Choosing the solutions with the initial conditions $(V_0^{(1)}, V_1^{(1)}) = (1, 0)$ and $(V_0^{(2)}, V_1^{(2)}) = (0, 1)$, one obtains the following hexagon in \mathbb{R}^2 : $\{(1, 0), (0, 1), (-1, 1), (-1, 0), (0, -1), (1, -1)\}$.



The index of this hexagon is 1.

(b) Consider the solution of Problem II $(a_1, a_2, a_3, a_4) = (2, 1, 2, 1)$ obtained from $(1, 1, 1)$ by applying one operation (1.2). Choosing the solutions with the same initial conditions as above, one obtains the following antiperiodic quadrilateral in \mathbb{R}^2 : $\{(1, 0), (0, 1), (-1, 2), (-1, 1)\}$.



whose index is $\frac{1}{2}$.

5.3. The index of a solution.

Proposition 5.5. *For a solution of Problem I or II obtained from (1.5) by a sequence of S operations (1.2) and R operations (1.3), the index of the corresponding broken line is equal to $\frac{1}{2}(R + 1)$.*

Proof. We need to show that the operations of the first type applied to solution of Problems I and II do not change the index of the corresponding broken line, while the operations of the second type increase this index by $\frac{1}{2}$.

An operation (1.2) adds one additional point, $V_i + V_{i+1}$, between the points V_i and V_{i+1} in the sequence of points $(V_i)_{i \in \mathbb{Z}}$. The resulting sequence is $(\dots, V_i, V_i + V_{i+1}, V_{i+1}, \dots)$, which has the same index as the initial one.

An easy computation shows that the operation (1.3) transforms the sequence of points $(V_i)_{i \in \mathbb{Z}}$ as follows:

$$(\dots, V_{i-1}, V_i, V_{i+1}, \dots) \mapsto (\dots, V_{i-1}, V_i, a'_i V_i - V_{i-1}, (a'_i - 1)V_i - V_{i-1}, -V_i, -V_{i+1}, \dots).$$

Indeed, the sequence on the right-hand-side is a solution of the equation (1.6) with coefficients

$$(a_1, \dots, a'_i, 1, 1, a''_i, \dots, a_n).$$

Therefore, the operation (1.3) rotates the picture by 180° and thus increases the index by $\frac{1}{2}$. \square

5.4. Non-osculating solutions and triangulations. Similarly to the classical Sturm theory of linear differential and difference equations, it is natural to introduce the following notion.

Definition 5.6. *A solution of Problem II whose the index is equal to $\frac{1}{2}$, is called non-osculating.*

In other words, a solution of Problem II is non-osculating the number R of surgery operations (1.3) needed to obtain this solution from the elementary solution $(a_1, a_2, a_3) = (1, 1, 1)$ equals zero. Note that solutions of Problem I cannot be non-osculating because R is odd in this case.

The class of non-osculating solutions of Problem II is precisely the totally positive solutions of Conway and Coxeter (see Appendix below). Indeed, if the number R equals zero, then the $3d$ -dissection is a triangulation, cf. Proposition 3.2.

Similarly, one can define the class of non-osculating solutions of Problem III as that corresponding to symmetric triangulations of a $2n$ -gon. Again, the non-osculating property is equivalent to that of total positivity.

6. AN APPLICATION: OSCILLATING TAME FRIEZES

We briefly introduce the notion of tame “oscillating” Coxeter friezes. We show that this notion is equivalent to solutions of Problem II. Theorems 2 and 1 then provide a classification of tame oscillating friezes. It is easy to see that oscillating Coxeter friezes satisfy the main properties of the classical friezes, such as Coxeter’s glide symmetry.

6.1. Classical Coxeter friezes. Coxeter’s frieze [7] is an array of $(n-1)$ infinite rows of *positive integers*, with the first and the last rows consisting of 1’s. Consecutive rows are shifted, and the so-called Coxeter *unimodular rule*:

$$\begin{array}{ccc} & b & \\ a & & d \\ & c & \end{array}, \quad ad - bc = 1,$$

is satisfied for every elementary 2×2 “diamond”.

The Conway-Coxeter theorem [6] provides a classification of Coxeter’s friezes. Every frieze corresponds to a triangulated n -gon, the rows 2 and $n-2$ being the quiddity of a triangulation; see Definition 1.1.

Example 6.1. For example, the frieze

$$\begin{array}{cccccc} \dots & 1 & 1 & 1 & 1 & 1 \\ & 1 & 3 & 1 & 2 & 2 & \dots \\ \dots & 2 & 2 & 1 & 3 & 1 \\ & 1 & 1 & 1 & 1 & 1 & \dots \end{array}$$

is the unique (up to a cyclic permutation) Coxeter frieze for $n = 5$. It corresponds to the quiddity $(a_1, a_2, a_3, a_4, a_5) = (1, 3, 1, 2, 2)$.

We refer to [18] for a survey on friezes and their connection to various topics.

6.2. Tameness. Let us relax the positivity assumption. Then frieze patterns may become undetermined, as discussed in [8], or very “wild”, and the classification of such friezes is out of reach; cf. [9]. An important property that we keep is that of tameness, first introduced in [3].

Definition 6.2. *A frieze is tame if the determinant of every elementary 3×3 -diamond vanishes.*

Remark 6.3. Note that every classical Coxeter frieze is tame. This follows easily from the positivity assumption.

6.3. Friezes corresponding to solutions of Problems II and III. It turns out that solutions of Problems II and III precisely correspond to tame friezes with $(a_i)_{i \in \mathbb{Z}}$ in the 2nd row. More precisely, we have the following

Proposition 6.4. *There is a one-to-one correspondence between*

- (i) *Solutions of Problem II and tame friezes with the 2nd row all positive integers;*
- (ii) *Solutions of Problem III and tame friezes with even n and the 2nd row of positive integers which are invariant under reflection in the middle row.*

Proof. The following fact was noticed in [6] for classical Coxeter friezes, and proved in [19] for tame friezes.

Lemma 6.5. *Every diagonal of a tame frieze is a solution of the equation (1.6) with coefficients $(a_i)_{i \in \mathbb{Z}}$ in the 2nd row of the frieze.*

Part (i) readily follows from the lemma, while Part (ii) is then a consequence of Coxeter’s glide symmetry. \square

Example 6.6. The solution of Problem III with $(a_1, a_2, a_3, a_4, a_5) = (2, 1, 1, 1, 1)$ generates the following tame frieze with $n = 10$:

$$\begin{array}{cccccccccccc}
 \dots & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & \dots \\
 & 2 & & 1 & & 1 & & 1 & & 1 & & 2 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & \dots \\
 \dots & 1 & & 0 & & 0 & & 0 & & 1 & & 1 & & 0 & & 0 & & 0 & & 0 & & 1 & & & & \dots \\
 & 0 & & -1 & & -1 & & -1 & & -1 & & 0 & & -1 & & -1 & & -1 & & -1 & & -1 & & -1 & & \dots \\
 \dots & -1 & & -2 & & -1 & & -2 & & -1 & & -1 & & -2 & & -1 & & -2 & & -1 & & -2 & & -1 & & \dots \\
 & 0 & & -1 & & -1 & & -1 & & -1 & & 0 & & -1 & & -1 & & -1 & & -1 & & -1 & & -1 & & \dots \\
 \dots & 1 & & 0 & & 0 & & 0 & & 1 & & 1 & & 0 & & 0 & & 0 & & 0 & & 1 & & & & \dots \\
 & 2 & & 1 & & 1 & & 1 & & 1 & & 2 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & \dots \\
 \dots & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & 1 & & \dots
 \end{array}$$

Every row is 5-periodic, and the frieze is symmetric under the reflection.

Remark 6.7. (a) The condition of *total positivity* for a solution (a_1, \dots, a_n) of one of the Problems I-III is precisely the condition that every entry of the frieze pattern with quiddity (a_1, \dots, a_n) is positive. This condition was introduced by Coxeter (see [7, 6]), and it is usually assumed in the literature on friezes; see [18]. We will discuss the condition of total positivity in more details in Appendix.

(b) A frieze pattern can be viewed as the “matrix” of a Sturm-Liouville operator (1.6) acting on the infinite-dimensional space of sequences of numbers. This point of view relates friezes to many different areas of mathematics. In particular, it allows one to apply the tools of linear algebra; see [19], and is useful for the spectral theory of linear difference operators; see [17].

7. APPENDIX: CONWAY-COXETER QUIDDITIES AND FAREY SEQUENCES

This section is an overview and does not contain new results. We describe the Conway-Coxeter theorem, formulated in terms of matrices $M_n(a_1, \dots, a_n)$, and a similar result in the case of Problem III, obtained in [5]. We also briefly discuss the relation to Farey sequences.

In the seminal paper [6], Conway and Coxeter classified solutions of Problem II² that satisfy a certain condition of total positivity. These are precisely the solutions obtained from the initial solution $(a_1, a_2, a_3) = (1, 1, 1)$ by a sequence of operations (1.2). Their classification of totally positive solutions beautifully relates Problem II to such classical subjects as triangulations of n -gons. Furthermore, the close relation of the topic to Farey sequences was already mentioned in [7]. It turns out that the Conway-Coxeter theorem implies some results of [13] about the index of a Farey sequence.

7.1. Total positivity. The class of totally positive solutions of Problem II can be defined in several equivalent ways. Coxeter [7] (and Conway and Coxeter [6]) assumed that all the entries of the corresponding frieze are positive.

Another simple definition is based on the properties of solutions of the Sturm-Liouville equation.

Definition 7.1. *A solution of Problem II is called totally positive if there exists a solution $(V_i)_{i \in \mathbb{Z}}$ of the equation (1.6) that does not change its sign on the interval $[1, \dots, n]$, i.e., the sequence (V_1, V_2, \dots, V_n) is positive or negative.*

In the context of Sturm oscillation theory, this case should be called “non-oscillant”, or “non-osculating”.

Remark 7.2. Note that since $M_n(a_1, \dots, a_n) = -\text{Id}$, every solution is n -anti-periodic, so that it must change sign on the interval $[1, n + 1]$.

²Conway and Coxeter worked with so-called frieze patterns (see Section 6 below), but the equivalence of their result to the classification of solutions of Problem II is a simple observation; see [3, 19].

Let us give an equivalent combinatorial definition. Consider the following tridiagonal $i \times i$ -determinant

$$K_i(a_1, \dots, a_i) = \begin{vmatrix} a_1 & 1 & & & \\ 1 & a_2 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & & 1 & a_{i-1} & 1 \\ & & & & 1 & a_i \end{vmatrix}.$$

This polynomial is nothing but the celebrated *continuant*, already known by Euler, and considered by many authors. It was proved by Coxeter [7] that the entries of a frieze pattern can be calculated as continuants of the entries of the second row.

It is also well-known, see, e.g., [3], (and can be easily checked directly) that the entries of the 2×2 matrix (1.1) can be explicitly calculated in terms of these determinants as follows:

$$M_n(a_1, \dots, a_n) = \begin{pmatrix} K_n(a_1, \dots, a_n) & -K_{n-1}(a_2, \dots, a_n) \\ K_{n-1}(a_1, \dots, a_{n-1}) & -K_{n-2}(a_2, \dots, a_{n-1}) \end{pmatrix}.$$

Definition 7.3. A solution (a_1, \dots, a_n) of Problem II is totally positive if

$$K_{j-1}(a_i, \dots, a_{i+j}) > 0$$

for all $j \leq n - 2$ and all i . Note that we use the cyclic ordering of the a_i .

Remark 7.4. (a) The condition $M_n(a_1, \dots, a_n) = -\text{Id}$ implies that $K_n(a_i, \dots, a_{i+n-1}) = 0$, for all i .

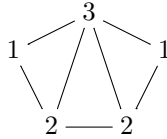
7.2. Triangulated n -gons. The Conway-Coxeter result states that totally positive solutions of Problem II are in one-to-one correspondence with triangulations of n -gons.

Given a triangulation of an n -gon, let a_i be the number of triangles adjacent to the i^{th} vertex. This yields an n -tuple of positive integers, (a_1, \dots, a_n) . Conway and Coxeter called an n -tuple obtained from such a triangulation a quiddity.

Theorem. [6] Any quiddity is a totally positive solution of Problem II, and every totally positive solution arises in this way.

A direct proof of the Conway-Coxeter theorem in terms of 2×2 -matrices is given in [10, 3]. For a simple proof, see also [15].

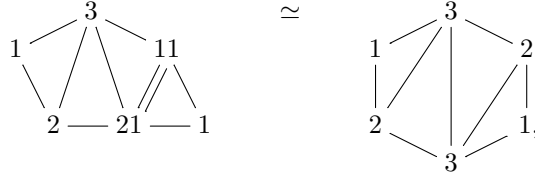
Example 7.5. For $n = 5$, the triangulation of the pentagon



generates a solution $(a_1, a_2, a_3, a_4, a_5) = (1, 3, 1, 2, 2)$ of Problem II. All other solutions for $n = 5$ are obtained by cyclic permutations of this one.

7.3. Gluing triangles. Obviously, every triangulation of an n -gon can be obtained from a triangle by adding new exterior triangles.

Example 7.6. Gluing a triangle to the above triangulated pentagon



one obtains the solution $(1, 3, 2, 1, 3, 2) = (1, 3, 1 + 1, 1, 2 + 1, 2)$ of Problem II, for $n = 6$.

An operation (1.2) applied to a quiddity consists in gluing a triangle to a triangulated n -gon, so that the Conway-Coxeter theorem implies the following statement (see also [10], Theorem 5.5).

Corollary 7.7. *Every totally positive solution of Problem II can be obtained from the initial solution $(a_1, a_2, a_3) = (1, 1, 1)$ by a sequence of operations (1.2).*

For a clear and detailed discussion; see [3].

7.4. Indices of Farey sequences as Conway-Coxeter quiddities. Relation to Farey sequences and negative continued fractions was already mentioned by Coxeter [7] (see also [20]).

Rational numbers in $[0, 1]$ whose denominator does not exceed N written in a form of irreducible fractions form the *Farey sequence* of order N . Elements of the Farey sequence, $v_1 = \frac{a_1}{b_1}$ and $v_2 = \frac{a_2}{b_2}$, are joined by an edge if and only if

$$|a_1 b_2 - a_2 b_1| = 1.$$

This leads to the classical notion of *Farey graph*. The Farey graph is often embedded into the hyperbolic plane, the edges being realized as geodesics joining rational points on the ideal boundary.

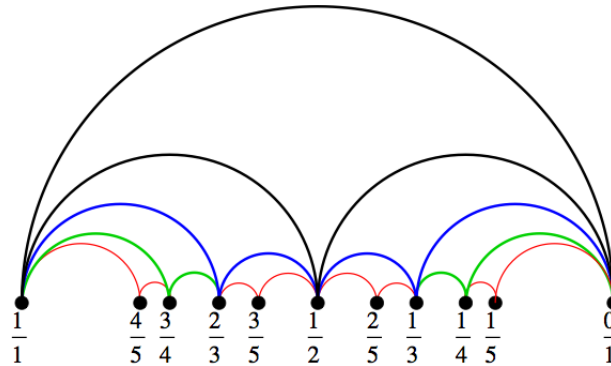


FIGURE 1. The Farey sequence of order 5 and the triangulated hendecagon.

The main properties of Farey sequences can be found in [14]. A simple but important property is that every Farey sequence forms a triangulated polygon in the Farey graph. A Conway-Coxeter quiddity is then precisely the index of a Farey sequence, defined in [13].

Remark 7.8. The Conway-Coxeter theorem implies that

$$a_1 + a_2 + \dots + a_n = 3n - 6.$$

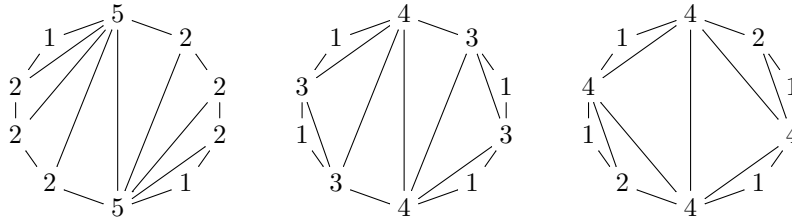
Indeed, the total number of triangles in a triangulation is $n - 2$, and each triangle has three angles that contribute to a quiddity. The above formula is equivalent to Theorem 1 of [13]. Moreover, it holds not only for the complete Farey sequence, but also for an arbitrary *path in the Farey graph*. Consider

the Farey sequence of order 5 presented in Figure 1. It has many different shorter paths, for instance, $\{\frac{1}{1}, \frac{2}{3}, \frac{3}{5}, \frac{1}{2}, \frac{1}{3}, \frac{0}{1}\}$.

7.5. Totally positive solutions of Problem III. A solution (a_1, \dots, a_n) of Problem III is totally positive if its double $(a_1, \dots, a_n, a_1, \dots, a_n)$ is a totally positive solution of Problem II. Every totally positive solution can be obtained from one of the solutions $(a_1, a_2) = (1, 2)$, or $(2, 1)$ by a sequence of operations (1.2).

The Conway-Coxeter theorem implies that there is a one-to-one correspondence between totally positive solutions of Problem III and *centrally symmetric* triangulations of $2n$ -gons; see also [5].

Example 7.9. There exist 70 different centrally symmetric triangulations of the decagon, for instance



The corresponding sequences $(a_1, a_2, a_3, a_4, a_5) = (5, 2, 2, 2, 1), (4, 3, 1, 3, 1), (4, 2, 1, 4, 1), \dots$ are totally positive solutions of Problem III.

The total number of totally positive solutions of Problem III is given by the central binomial coefficient $\binom{2n}{n} = 1, 2, 6, 20, 70, 252, 924, \dots$

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